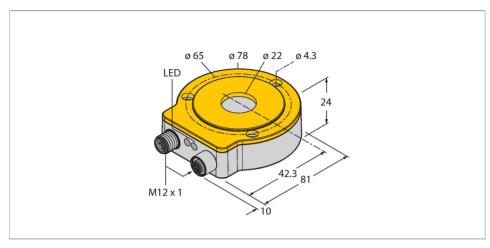


RI360P0-QR24M0-CNX4-2H1150 Contactless Encoder – CANopen Premium Line



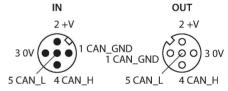
Technical data

| Туре | RI360P0-QR24M0-CNX4-2H1150 |
|---|--|
| ID no. | 1590914 |
| Measuring principle | Inductive |
| Max. Rotational Speed | 2000 rpm |
| | Determined with standardized construction, with a steel shaft Ø 20 mm, L = 50 mm and reducer Ø 20 mm |
| Starting torque shaft load (radial / axial) | not applicable, because of contactless measuring principle |
| Measuring range | 0360 ° |
| Nominal distance | 1.5 mm |
| Repeat accuracy | ≤ 0.01 % of full scale |
| Linearity deviation | ≤ 0.05 %f.s. |
| Temperature drift | ≤ ± 0.003 % / K |
| Ambient temperature | -25+85 °C |
| Operating voltage | 1030 VDC |
| Residual ripple | ≤ 10 % U _{ss} |
| Isolation test voltage | ≤ 0.5 kV |
| Wire breakage/Reverse polarity protection | yes (voltage supply) |
| Output type | Absolute singleturn |
| Resolution singleturn | 16 Bit |
| Communication protocol | CANopen |
| Interface | CANopen, DS406 device profile, LSS DS 305 |

Features

- Compact, rugged housing
- Many mounting possibilities
- ■Status displayed via LED
- Positioning element and aluminium ring not incl.
- ■CANopen interface
- ■Baud rate 10 kbps up to 1 Mbps; Factory setting: 125 kbps
- Node address 1 to 127; Factory setting 3
- Terminating resistor switched in via CANopen device access
- Immune to electromagnetic interference
- ■10 ... 30 VDC
- ■M12 x 1 male, 5-pin, CAN in, CAN out
- Acc. to CiA DS-301, CiA 305, CiA 406

Wiring diagram



Functional principle

The measuring principle of inductive angle sensors is based on oscillation circuit coupling between the positioning element and the sensor, whereby an output signal is provided proportional to the angle of the positioning element. The rugged sensors are wear and maintenance-free, thanks to the contactless operating principle. They convince through their excellent repeatability, resolution and linearity within a broad temperature range. The innovative technology ensures a high immunity to electromagnetic DC and AC fields.

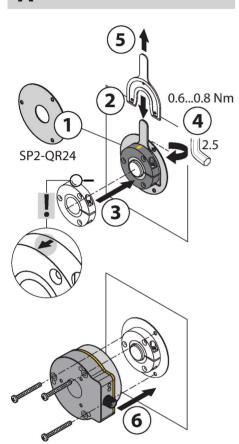




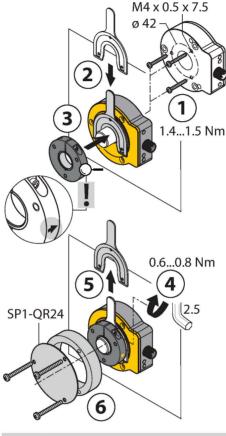
| Node ID | 1127; Werkseinstellung: 3 |
|---|---|
| Baud rate | 10, 20, 50, 125, 250, 500, 800 and 125 kbps, factory setting 125 kbps |
| Sample rate | 800 Hz |
| Current consumption | < 60 mA |
| Design | QR24 |
| Dimensions | 81 x 78 x 24 mm |
| Flange type | Flange without mounting element |
| Shaft Type | Hollow shaft |
| Shaft diameter D [mm] | 6 6.35 9.525 10 12 12.7 14 15.875 19.05 |
| Housing material | Metal/plastic, ZnAlCu1/PBT-GF30-V0 |
| Electrical connection | Connector, M12 × 1 |
| Vibration resistance | 55 Hz (1 mm) |
| Vibration resistance (EN 60068-2-6) | 20 g; 103000 Hz; 50 cycles; 3 axes |
| Shock resistance (EN 60068-2-27) | 100 g; 11 ms ½ sinus; each 3x; 3 axes |
| Continuous shock resistance (EN | 40 g; 6 ms ½ sinus; each 4000 x; 3 axes |
| 60068-2-29) | |
| Protection class | IP68 IP69K |
| | |
| Protection class | IP69K 138 years acc. to SN 29500 (Ed. 99) 40 |
| Protection class MTTF | IP69K 138 years acc. to SN 29500 (Ed. 99) 40 °C |
| Protection class MTTF Power-on indication | IP69K 138 years acc. to SN 29500 (Ed. 99) 40 °C LED, Green |

Mounting instructions

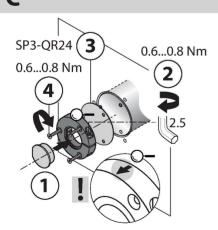
Mounting instructions/Description

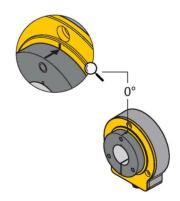


B



Default: 0°





Extensive range of mounting accessories for easy adaptation to many different shaft diameters. Based on the functional principle of RLC coupling, the encoder is immune to magnetized metal splinters and other interferences.

The adjacent figure shows the two separate units, sensor and positioning element. Mounting option A:

First, interconnect positioning element and rotatable shaft with the bracket. Then place the encoder above the rotating part in such a way that you get a tight and protected unit. Mounting option B:

Push the encoder on the back site of the shaft and fasten it to the machine. Then clamp the positioning element to the shaft with the bracket.

Mounting option C:

If the positioning element is screwed on a rotating machine part and not to a shaft, you must first put on the dummy plug RA8-QR24. Then tie up the bracket. Screw on the encoder via the three bores.

When mounting, ensure that the positioning element is correctly aligned towards the sensor's active face. For correct fitting see arrow on the edge of the positioning element. (Arrow must point in direction of sensor)

arrow on the edge of the positioning element. (Arrow must point in direction of sensor)

Due to the separate installation of positioning element and sensor no electrical currents or harmful mechanical forces are transmitted via the shaft to the sensor. The encoder also offers a high degree of protection for life and stays permanently sealed.

The accessories enclosed in the delivery help to mount encoder and positioning element at an optimal distance from each other. LEDs indicate the switching status. Optionally, you can use the shield plates which are included in the accessories to increase the allowed distance between positioning element and sensor.

Status / Power LED:

Green:

Sensor is properly supplied, positioning element in the coverage
Yellow:
Positioning element is in the measuring range, signal low (e.g. distance too large)
Yellow flashing:
Positioning element is outside the coverage

Status CAN

Green / Red:CAN communication active / not active

Red / Green alternating:LSS services active

Green flashing Pre-operational state

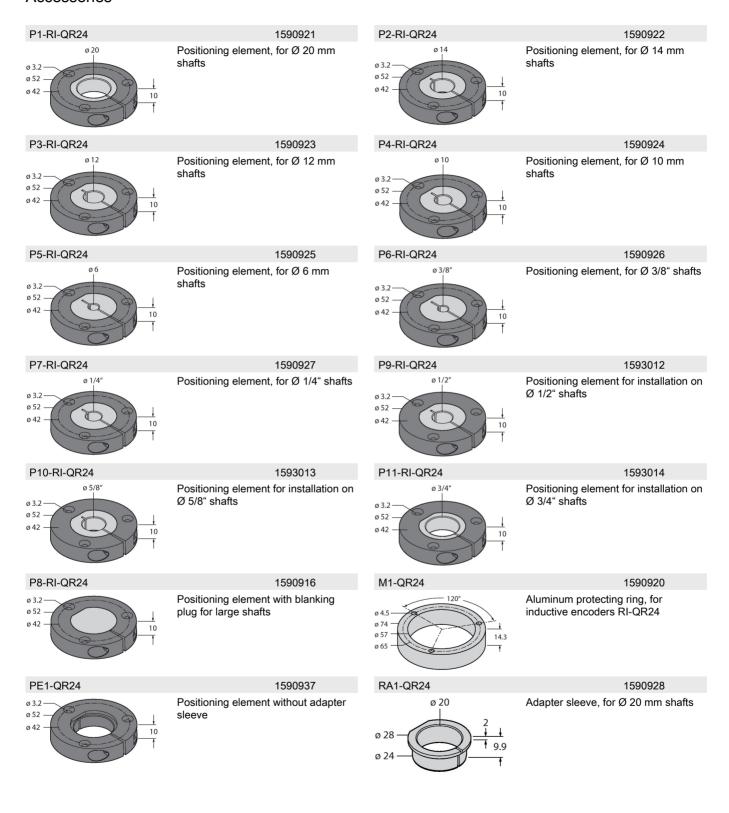
Green 1 x flashing:CAN communication stopped

Red 2 x flashing:Error control event

Red 3 x flashing:Sync Error

TURCK

Accessories



4|6

1590930

Adapter sleeve, for Ø 12 mm shafts

1590929

Adapter sleeve, for Ø 14 mm shafts

RA3-QR24

ø 12

RA2-QR24

ø 14



Bus cable for CAN (DeviceNet, -CANopen), M12 coupling, straight, cable length: 5m, jacket material: PUR, anthracite; cULus approval; other cable lengths and qualities available, see www.turck.com