## Product data sheet Characteristics



# ATV71HU15M3Z variable speed drive ATV71 - 1.5kW-2HP - 240V -EMC filter-w/o graphic terminal

Product availability: Non-Stock - Not normally stocked in distribution facility

Price\*: 647.90 USD

Commercial Status	Commercialised
Range of product	Altivar 71
Product or component type	Variable speed drive
Product specific application	Complex, high-power machines
Component name	ATV71
Motor power kW	1.5 kW at 200240 V 3 phases 0.75 kWat 200240 V single phase
Motor power hp	2 hp at 200240 V 3 phases 1 hpat 200240 V single phase
Motor cable length	
[Us] rated supply voltage	200240 V (- 1510 %)
Phase	3 phases Single phase
Line current	9.9 Afor 240 V single phase 0.75 kW / 1 hp 9.6 Afor 240 V 3 phases 1.5 kW / 2 hp 12 Afor 200 V single phase 0.75 kW / 1 hp 11.3 Afor 200 V 3 phases 1.5 kW / 2 hp
EMC filter	Integrated
Assembly style	With heat sink
Variant	Without remote graphic terminal
Apparent power	4 kVAat 240 V 3 phases 1.5 kW / 2 hp 2.4 kVAat 240 V single phase 0.75 kW / 1 hp
Prospective line Isc	<= 5 kA, single phase <= 5 kA, 3 phases
Nominal output current	8 Aat 4 kHz 230 V 3 phases / 2 hp 4.8 Aat 4 kHz 230 V single phase / 1 hp
Maximum transient current	13.2 Afor 2 s 3 phases 1.5 kW / 2 hp 12 Afor 60 s 3 phases 1.5 kW / 2 hp 7.9 Afor 2 s single phase 0.75 kW / 1 hp 7.2 Afor 60 s single phase 0.75 kW / 1 hp
Speed drive output frequency	0.1599 Hz
Nominal switching frequency	4 kHz
Switching frequency	416 kHz with derating factor 116 kHz adjustable
Asynchronous motor control profile	ENA (Energy adaptation) system for unbalanced loads Flux vector control (FVC) with sensor (current vector) Sensorless flux vector control (SFVC) (voltage or current vector) Voltage/Frequency ratio (2 or 5 points)



## Complementary

Jompienieniary				
Product destination	Asynchronous motors Synchronous motors			
Supply voltage limits	170264 V			
Supply frequency	5060 Hz (- 55 %)			
Network frequency limits	47.563 Hz			
Speed range	150for synchronous motor in open-loop mode, without speed feedback 11000 asynchronous motor in closed-loop mode with encoder feedback 1100 asynchronous motor in open-loop mode, without speed feedback			
Speed accuracy	+/- 10 % of nominal slip 0.2 Tn to Tn torque variation without speed feedback +/- 0.01 % of nominal speed 0.2 Tn to Tn torque variation in closed-loop mode with encoder feedback			
Torque accuracy	+/- 5 % in closed-loop mode with encoder feedback +/- 15 % in open-loop mode, without speed feedback			
Transient overtorque	220 % of nominal motor torque +/- 10 %for 2 s 170 % of nominal motor torque +/- 10 %for 60 s every 10 minutes			
Braking torque	30 % without braking resistor < 150 % with braking or hoist resistor			
Synchronous motor control profile	Vector control without speed feedback			
Regulation loop	Adjustable PI regulator			
Motor slip compensation	Adjustable Automatic whatever the load Not available in voltage/frequency ratio (2 or 5 points) Suppressable			
Local signalling	1 LED red presence of drive voltage			
Output voltage	<= power supply voltage			
nsulation	Electrical between power and control			
Type of cable	Without mounting kit: 1-strand IEC cableat 113 °F (45 °C), copper 90 °C XLPE/EPR Without mounting kit: 1-strand IEC cableat 113 °F (45 °C), copper 70 °C PVC With an IP21 or an IP31 kit: 3-strand IEC cableat 104 °F (40 °C), copper 70 °C PVC With a NEMA Type1 kit: 3-strand UL 508 cableat 104 °F (40 °C), copper 75 °C PVC			
Electrical connection	L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA, PB terminal 4 mm² / AWG 10			
	AI1-/AI1+, AI2, AO1, R1A, R1B, R1C, R2A, R2B, LI1LI6, PWR terminal 2.5 mm² / AWG 14			
Tightening torque	L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA, PB 12.39 lbf.in (1.4 N.m) AI1-/AI1+, AI2, AO1, R1A, R1B, R1C, R2A, R2B, LI1LI6, PWR 5.31 lbf.in (0.6 N.m)			
Supply	Internal supply, 24 V DC, voltage limits 2127 V, <= 200 mAfor overload and short- circuit protection Internal supply for reference potentiometer (1 to 10 kOhm), 10.5 V DC +/- 5 %, <= 10 mAfor overload and short-circuit protection			
Analogue input number	2			
Analogue input type	Al2 software-configurable voltage 010 V DC, input voltage 24 V max, impedance 30000 Ohm, resolution 11 bits Al2 software-configurable current 020 mA, impedance 242 Ohm, resolution 11 bits Al1-/Al1+ bipolar differential voltage +/- 10 V DC, input voltage 24 V max, resolution 11 bits + sign			
Sampling duration	LI6 (if configured as logic input) 2 ms, +/- 0.5 ms discrete input(s) LI1LI5 2 ms, +/- 0.5 ms discrete input(s) AI2 2 ms, +/- 0.5 ms analog input(s) AI1-/AI1+ 2 ms, +/- 0.5 ms analog input(s)			
Response time	R2A, R2B 7 ms, tolerance +/- 0.5 ms discrete output(s) R1A, R1B, R1C 7 ms, tolerance +/- 0.5 ms discrete output(s) AO1 2 ms, tolerance +/- 0.5 ms analog output(s) <= 100 ms in STO (Safe Torque Off)			
Accuracy	AO1 +/- 1 % for a temperature variation 60 °C Al2 +/- 0.6 % for a temperature variation 60 °C Al1-/Al1+ +/- 0.6 % for a temperature variation 60 °C			
1.	AO1 +/- 0.2 %			
Linearity error	AI1-/AI1+, AI2 +/- 0.15 % of maximum value			



Analogue output type	AO1 software-configurable voltage 010 V DC, impedance 470 Ohm, resolution 10 bits AO1 software-configurable current 020 mA, impedance 500 Ohm, resolution 10 bits AO1 software-configurable logic output 10 V <= 20 mA
Discrete output number	2
Discrete output type	R2A, R2B configurable relay logic NO, electrical durability 100000 cycles R1A, R1B, R1C configurable relay logic NO/NC, electrical durability 100000 cycles
Minimum switching current	Configurable relay logic 3 mAat 24 V DC
Maximum switching current	R1, R2 on resistive load, 5 Aat 30 V DC, cos phi = 1, R1, R2 on resistive load, 5 Aat 250 V AC, cos phi = 1, R1, R2 on inductive load, 2 Aat 30 V DC, cos phi = 0.4, R1, R2 on inductive load, 2 Aat 250 V AC, cos phi = 0.4,
Discrete input number	7
Discrete input type	PWR: safety input 24 V DC, impedance: 1500 Ohm conforming to ISO 13849-1 level d LI6: switch-configurable PTC probe 06, impedance: 1500 Ohm LI6: switch-configurable 24 V DC with level 1 PLC, impedance: 3500 Ohm LI1LI5: programmable 24 V DC with level 1 PLC, impedance: 3500 Ohm
Discrete input logic	LI6 (if configured as logic input) positive logic (source), < 5 V (state 0), > 11 V (state 0) LI6 (if configured as logic input) negative logic (sink), > 16 V (state 0), < 10 V (state 0) LI1LI5 positive logic (source), < 5 V (state 0), > 11 V (state 0) LI1LI5 negative logic (sink), > 16 V (state 0), < 10 V (state 0)
Acceleration and deceleration ramps	Automatic adaptation of ramp if braking capacity exceeded, by using resistor Linear adjustable separately from 0.01 to 9000 s S, U or customized
Braking to standstill	By DC injection
Protection type	Motor thermal protection Motor power removal Motor motor phase break Drive thermal protection Drive short-circuit between motor phases Drive overvoltages on the DC bus Drive overheating protection Drive overcurrent between output phases and earth Drive line supply undervoltage Drive line supply overvoltage Drive input phase breaks Drive break on the control circuit Drive against input phase loss Drive against exceeding limit speed
Insulation resistance	> 1 mOhm at 500 V DC for 1 minute to earth
Frequency resolution	Display unit 0.1 Hz Analog input 0.024/50 Hz
Communication port protocol	CANopen Modbus
Type of connector	Male SUB-D 9 on RJ45 CANopen 1 RJ45 Modbus on terminal 1 RJ45 Modbus on front face
Physical interface	2-wire RS 485 Modbus
Transmission frame	RTU Modbus
Transmission rate	20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps CANopen 9600 bps, 19200 bps Modbus on front face 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps Modbus on terminal
Data format	8 bits, odd even or no configurable parity Modbus on terminal 8 bits, 1 stop, even parity Modbus on front face
Number of addresses	1247 Modbus 1127 for CANopen
Method of access	Slave CANopen
Marking	CE
Operating position	Vertical +/- 10 degree
Height	9.06 in (230 mm)
Depth Width	6.89 in (175 mm)



6.61 lb(US) (3 kg)

	0.01 Ib(03) (3 kg)
ion card	Profibus DP V1 communication card Profibus DP communication card Overhead crane card Modbus/Uni-Telway communication card Modbus TCP communication card
	Modbus Plus communication card Interface card for encoder Interbus-S communication card I/O extension card Fipio communication card Ethernet/IP communication card DeviceNet communication card Controller inside programmable card CC-Link communication card

## Environment

Noise level	43 dB conforming to 86/188/EEC
Dielectric strength	4230 V DC between control and power terminals 2830 V DC between earth and power terminals
Electromagnetic compatibility	Voltage dips and interruptions immunity test conforming to IEC 61000-4-11 Radiated radio-frequency electromagnetic field immunity test conforming to IEC 61000-4-3 level 3 Electrostatic discharge immunity test conforming to IEC 61000-4-2 level 3 Electrical fast transient/burst immunity test conforming to IEC 61000-4-4 level 4 Conducted radio-frequency immunity test conforming to IEC 61000-4-6 level 3 1.2/50 µs - 8/20 µs surge immunity test conforming to IEC 61000-4-5 level 3
Standards	EN 55011 class A group 1 EN 61800-3 environments 1 category C2 EN 61800-3 environments 2 category C2 EN/IEC 61800-3 EN/IEC 61800-5-1 IEC 60721-3-3 class 3C1 IEC 60721-3-3 class 3S2 UL Type 1
Product certifications	CSA C-Tick GOST NOM 117 UL
Pollution degree	2 conforming to EN/IEC 61800-5-1
IP degree of protection	IP54 on lower part conforming to EN/IEC 61800-5-1 IP54 on lower part conforming to EN/IEC 60529 IP41 on upper part conforming to EN/IEC 61800-5-1 IP41 on upper part conforming to EN/IEC 60529 IP21 conforming to EN/IEC 61800-5-1 IP21 conforming to EN/IEC 60529 IP20 on upper part without blanking plate on cover conforming to EN/IEC 61800-5- IP20 on upper part without blanking plate on cover conforming to EN/IEC 60529
Vibration resistance	1.5 mm peak to peak (f = 313 Hz) conforming to EN/IEC 60068-2-6 1 gn (f = 13200 Hz) conforming to EN/IEC 60068-2-6
Shock resistance	15 gn 11 ms conforming to EN/IEC 60068-2-27
Relative humidity	595 % without dripping water conforming to IEC 60068-2-3 595 % without condensation conforming to IEC 60068-2-3
Ambient air temperature for operation	14122 °F (-1050 °C) without derating
Ambient air temperature for storage	-13158 °F (-2570 °C)
Operating altitude	3280.849842.52 ft (10003000 m) with current derating 1 % per 100 m <= 3280.84 ft (1000 m) without derating
	-



Ordering and shipping details		
Category	22130 - ATV71 - 1/2 THRU 5HP DRIVES	
Discount Schedule	CP4C	
Nbr. of units in pkg.	1	
Product availability	Non-Stock - Not normally stocked in distribution facility	
Returnability	Ν	
Country of origin	ID	

## Contractual warranty

Warranty period

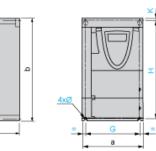
18 months



# ATV71HU15M3Z

## Variable Speed Drives without Graphic Display Terminal

## Dimensions without Option Card



#### Dimensions in mm

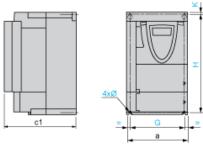
с

а	b	С	G	Н	к	Ø
130	230	149	113.5	220	5	5

#### Dimensions in in.

а	b	c	G	Н	к	Ø
5.11	9.05	5.86	4.46	8.66	0.19	0.19

### Dimensions with 1 Option Card (1)



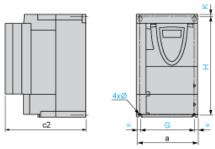
#### Dimensions in mm

а	c1	G	Н	к	Ø	
130	172	113.5	220	5	5	
Dimensions in in.						
а	c1	G	Н	к	Ø	
5.11	6.77	4.46	8.66	0.19	0.19	

(1) Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.



## Dimensions with 2 Option Cards (1)



#### Dimensions in mm

130 195 113.5 220 5 5	а	c2	G	Н	К	Ø
	130	195	113.5	220	5	5

#### Dimensions in in.

а	c2	G	Н	К	Ø
5.11	7.68	4.46	8.66	0.19	0.19

(1) Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.



# ATV71HU15M3Z

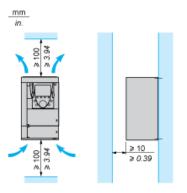
#### Mounting Recommendations

Depending on the conditions in which the drive is to be used, its installation will require certain precautions and the use of appropriate accessories.

Install the unit vertically:

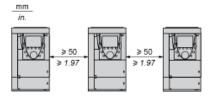
- Avoid placing it close to heating elements
- Leave sufficient free space to ensure that the air required for cooling purposes can circulate from the bottom to the top of the unit.

#### Clearance

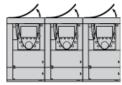


### Mounting Types

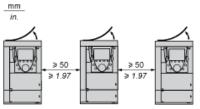
Type A Mounting



Type B Mounting



Type C Mounting



By removing the protective blanking cover from the top of the drive, the degree of protection for the drive becomes IP 20.

The protective blanking cover may vary according to the drive model (refer to the user guide).

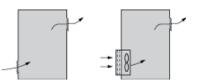
The protective blanking cover must be removed from ATV 71P ••• N4Z drives when they are mounted in a dust and damp proof enclosure.



### Ventilation

To ensure proper air circulation in the drive:

- Fit ventilation grilles.
- Ensure that there is sufficient ventilation. If there is not, install a forced ventilation unit with a filter. The openings and/or fans must provide a flow rate at least equal to that of the drive fans (refer to the product characteristics).



- Use special filters with IP 54 protection.
- Remove the blanking cover from the top of the drive.

### Dust and Damp Proof Metal Enclosure (IP 54)

The drive must be mounted in a dust and damp proof enclosure in certain environmental conditions: dust, corrosive gases, high humidity with risk of condensation and dripping water, splashing liquid, etc.

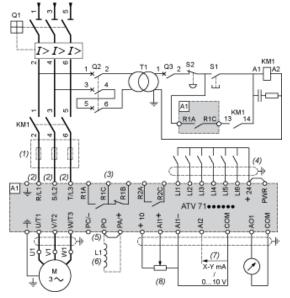
This enables the drive to be used in an enclosure where the maximum internal temperature reaches 50°C.



# ATV71HU15M3Z

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

#### Three-Phase Power Supply with Upstream Breaking via Contactor



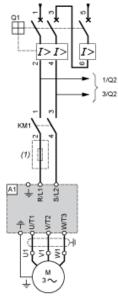
A1 ATV71 drive

- KM1 Contactor
- L1 DC choke
- Q1 Circuit-breaker
- Q2 GV2 L rated at twice the nominal primary current of T1
- Q3 GB2CB05
- S1, XB4 B or XB5 A pushbuttons
- S2
- T1 100 VA transformer 220 V secondary
- (1) Line choke (three-phase); mandatory for ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (2) For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections diagram.
- (3) Fault relay contacts. Used for remote signalling of the drive status.
- (4) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (5) There is no PO terminal on ATV71HC11Y...HC63Y drives.
- (6) Optional DC choke for ATV71H•••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV71HD55M3X, HD75M3X, ATV71HD90N4...HC50N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it.
- (7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (8) Reference potentiometer.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1





## A1 ATV71 drive

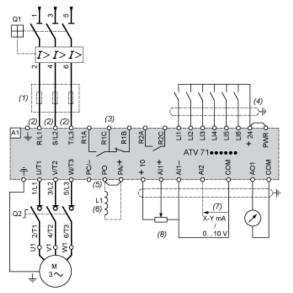
- KM1 Contactor
- Q1 Circuit-breaker
- Q2 GV2 L rated at twice the nominal primary current of T1  $\,$
- (1) Line Choke (single-phase); mandatory for ATV71HU40M3...HU75M3 drives with a 200...240 V 50/60 Hz single-phase power supply.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1



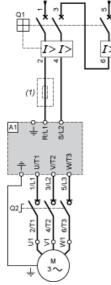
Three-Phase Power Supply with Downstream Breaking via Switch Disconnector



- A1 ATV71 drive
- L1 DC choke
- Q1 Circuit-breaker
- Q2 Switch disconnector (Vario)
- (1) Line choke (three-phase), mandatory for ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (2) For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections diagram.
- (3) Fault relay contacts. Used for remote signalling of the drive status.
- (4) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (5) There is no PO terminal on ATV71HC11Y...HC63Y drives.
- (6) Optional DC choke for ATV71H•••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV71HD55M3X, HD75M3X, ATV71HD90N4...HC50N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it.
- (7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (8) Reference potentiometer.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1



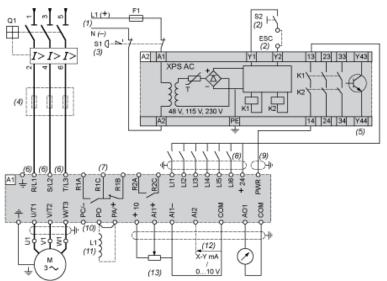
- A1 ATV71 drive
- Q1 Circuit-breaker
- Q2 Switch disconnector (Vario)

(1) Line Choke (single-phase); mandatory for ATV71HU40M3...HU75M3 drives with a 200...240 V 50/60 Hz single-phase power supply. All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 0 According to IEC/EN 60204-1



### Three-Phase Power Supply, Low Inertia Machine, Vertical Movement

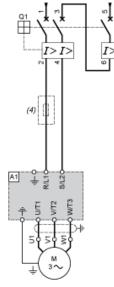


#### A1 ATV71 drive

- A2 Preventa XPS AC safety module for monitoring emergency stops and switches. One safety module can manage the "Power Removal" function for several drives on the same machine. In this case, each drive must connect its PWR terminal to its + 24 V via the safety contacts on the XPS AC module. These contacts are independent for each drive.
- F1 Fuse
- L1 DC choke
- Q1 Circuit-breaker
- S1 Emergency stop button with 2 contacts
- S2 XB4 B or XB5 A pushbutton
- (1) Power supply: 24 Vdc or Vac, 48 Vac, 115 Vac, 230 Vac.
- (2) S2: resets XPS AC module on power-up or after an emergency stop. ESC can be used to set external starting conditions.
- (3) Requests freewheel stopping of the movement and activates the "Power Removal" safety function.
- (4) Line choke (three-phase), mandatory for and ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (5) The logic output can be used to signal that the machine is in a safe stop state.
- (6) For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections diagram.
- (7) Fault relay contacts. Used for remote signalling of the drive status.
- (8) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (9) Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm /0.09 in., maximum length 15 m / 49.21 ft. The cable shielding must be earthed.
- (10) There is no PO terminal on ATV71HC11Y...HC63Y drives.
- (11) Optional DC choke for ATV71H•••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV71HD55M3X, HD75M3X, ATV71HD90N4...HC50N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it.
- (12) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (13) Reference potentiometer.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

# Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 0 According to IEC/EN 60204-1



- A1 ATV71 drive
- Q1 Circuit-breaker

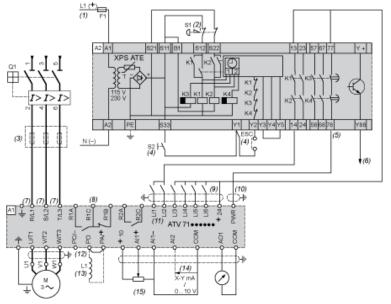
(4) Line Choke (single-phase); mandatory for ATV71HU40M3...HU75M3 drives with a 200...240 V 50/60 Hz single-phase power supply.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 1 According to IEC/EN 60204-1



### Three-Phase Power Supply, High Inertia Machine

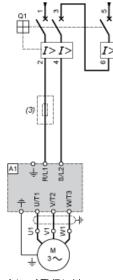


- A1 ATV71 drive
- A2 Preventa XPS ATE safety module for monitoring emergency stops and switches. One safety module can manage the "Power Removal" (5) safety function for several drives on the same machine. In this case the time delay must be adjusted on the drive controlling the motor that
- (c) safety function for several drives on the same machine. In this case the time delay must be adjusted on the drive contacting the motor that requires the longest stopping time. In addition, each drive must connect its PWR terminal to its + 24 V via the safety contacts on the XPS ATE module. These contacts are independent for each drive.
- F1 Fuse
- L1 DC choke
- Q1 Circuit-breaker
- S1 Emergency stop button with 2 N/C contacts
- S2 Run button
- (1) Power supply: 24 Vdc or Vac, 115 Vac, 230 Vac.
- (2) Requests controlled stopping of the movement and activates the "Power Removal" safety function.
- (3) Line choke (three-phase), mandatory for ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (4) S2: resets XPS ATE module on power-up or after an emergency stop. ESC can be used to set external starting conditions.
- (5) For stopping times requiring more than 30 seconds in category 1, use a Preventa XPS AV safety module which can provide a maximum time delay of 300 seconds.
- (6) The logic output can be used to signal that the machine is in a safe state.
- (7) For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections diagram.
- (8) Fault relay contacts. Used for remote signalling of the drive status.
- (9) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (10) Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm/0.09 in., maximum length 15 m/49.21 ft. The cable shielding must be earthed.
- (11) Logic inputs LI1 and LI2 must be assigned to the direction of rotation: LI1 in the forward direction and LI2 in the reverse direction.
- (12) There is no PO terminal on ATV71HC11Y...HC63Y drives.
- (13) Optional DC choke for ATV71H•••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV71HD55M3X, HD75M3X, ATV71HD90N4...HC50N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it.
- (14) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (15) Reference potentiometer.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 1 According to IEC/EN 60204-1





- A1 ATV71 drive
- Q1 Circuit-breaker

(3) Line Choke (single-phase); mandatory for ATV71HU40M3...HU75M3 drives with a 200...240 V 50/60 Hz single-phase power supply.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.



Product data sheet Performance Curves

# ATV71HU15M3Z

## **Derating Curves**

The derating curves for the drive nominal current (In) depend on the temperature, the switching frequency and the mounting type. For intermediate temperatures (e.g. 55°C), interpolate between 2 curves.

